

Putting Theory to Work: From Learning Bounds to Meta-Learning Algorithms

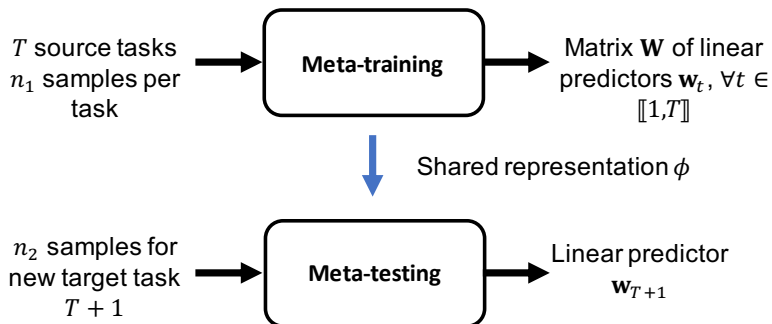
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Goal: Minimize excess risk $ER = \mathcal{L}(\phi^*, \mathbf{w}_{T+1}^*) - \mathcal{L}(\phi, \mathbf{w}_{T+1})$,

- ▶ True risk \mathcal{L}
- ▶ optimal weights ϕ^*
- ▶ \mathbf{w}_{T+1}^* ideal target linear predictor.

Assumption 1: Diversity of the source tasks

Optimal predictors $\mathbf{W}^* = [\mathbf{w}_1^*, \dots, \mathbf{w}_T^*]$ cover all the directions evenly

Assumption 2: Constant classification margin

Norm of $\{\mathbf{w}_t^*\}_{t \in [1, T]}$ should not increase with T

$$\text{if satisfied, } ER(\phi, \mathbf{w}_{T+1}) \leq O\left(\frac{1}{n_1 T} + \frac{1}{n_2}\right) \quad [2, 5]$$

✓ All source and target data are useful to decrease the excess risk

Ensuring Assumption 1: Add spectral or entropic regularization

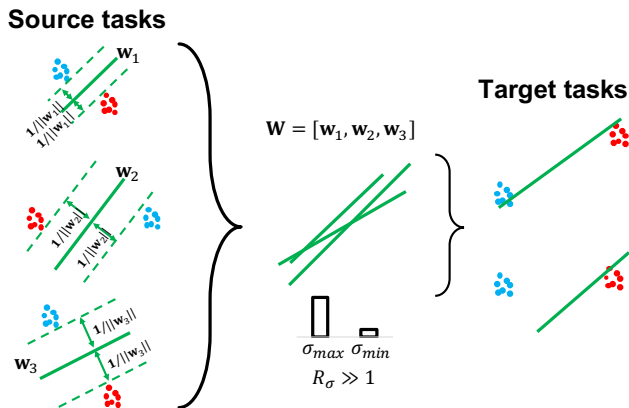
$$R_{\sigma}(\mathbf{W}) = \frac{\sigma_{\max}(\mathbf{W})}{\sigma_{\min}(\mathbf{W})} \quad \text{or} \quad H_{\sigma}(\mathbf{W}) = -\sum_{i=1}^N \text{softmax}(\sigma(\mathbf{W}))_i \cdot \log \text{softmax}(\sigma(\mathbf{W}))_i$$

- ✓ Regularizing with $R_{\sigma}(\mathbf{W})$ or $H_{\sigma}(\mathbf{W})$ leads to a better coverage of the searched space

Ensuring Assumption 2: Add norm regularization/normalization for linear predictors

- ✓ Normalizing predictors ensure constant margin that does not change with T

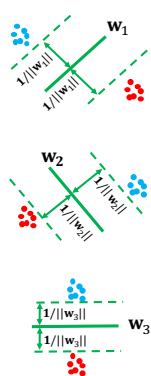
Without regularization



✗ Linear predictors cover only part of the space or over-specialize to the tasks

With proposed regularization

Source tasks

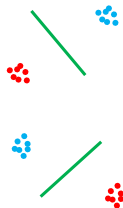


$$W = [w_1, w_2, w_3]$$



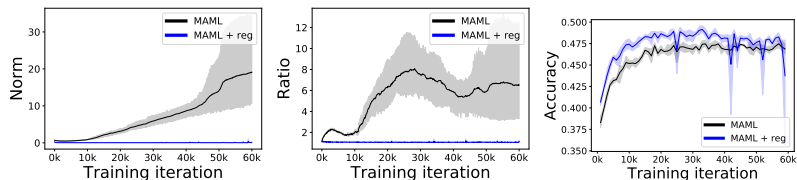
$$\begin{matrix} \square & \square \\ \sigma_{max} & \sigma_{min} \\ R_{\sigma} \approx 1 \end{matrix}$$

Target tasks

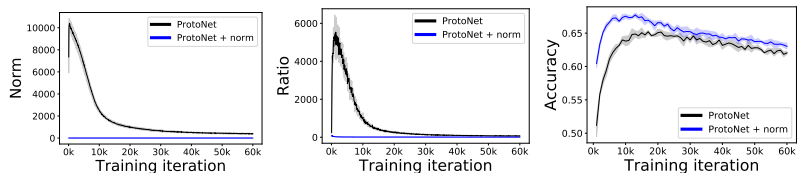


- ✓ Assumption 1 makes sure that linear predictors are complementary
- ✓ Assumption 2 avoids under- or over-specialization to the tasks

Tracking the ratio and the norm



✗ MAML [3] does not verify the assumptions



✓ PROTONET [4] naturally verifies the assumptions

Accuracy gap with regularization

Dataset	Episodes	MAML[3]	PROTONET[4]	BASELINE[1]	BASELINE++[1]
Omniglot	20-way 1-shot	+3.95*	+0.33*	-13.2*	-7.29*
	20-way 5-shot	+1.17*	+0.01	+0.66*	-2.24*
minilImageNet	5-way 1-shot	+1.23*	+0.76*	+1.52*	+0.39
	5-way 5-shot	+1.96*	+2.03*	+1.66*	-0.13
tieredImageNet	5-way 1-shot	+1.42*	+2.10*	+5.43*	+0.28
	5-way 5-shot	+2.66*	+0.23	+1.92*	-0.72

✓ Enforcing the assumptions leads to **better generalization** when not verified naturally

- ✓ **Practical ways** to enforce **theoretical** assumptions
- ✓ Some models **naturally fulfill** them
- ✓ Our regularization allows to **learn faster** with **better generalization**

- [1] Wei-Yu Chen, Yu-Chiang Frank Wang, Yen-Cheng Liu, Zsolt Kira, and Jia-Bin Huang.
A closer look at few-shot classification.
In *ICLR*, 2019.
- [2] Simon S. Du, Wei Hu, Sham M. Kakade, Jason D. Lee, and Qi Lei.
Few-Shot Learning via Learning the Representation, Provably.
In *arXiv:2002.09434*, 2020.
- [3] Chelsea Finn, Pieter Abbeel, and Sergey Levine.
Model-Agnostic Meta-Learning for Fast Adaptation of Deep Networks.
In *International Conference on Machine Learning*, 2017.
- [4] Jake Snell, Kevin Swersky, and Richard S. Zemel.
Prototypical Networks for Few-shot Learning.
In *Advances in Neural Information Processing Systems*, 2017.
- [5] Nilesch Tripuraneni, Chi Jin, and Michael I. Jordan.
Provable Meta-Learning of Linear Representations.
In *arXiv:2002.11684*, 2020.

Arxiv paper:



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 <https://qbouniot.github.io>

Thank you for listening !



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